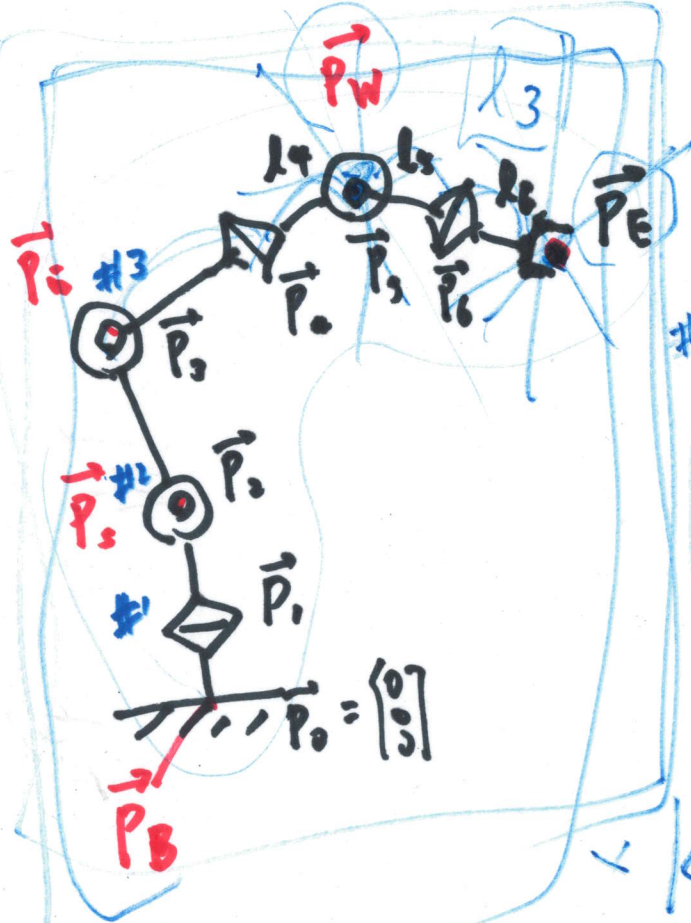
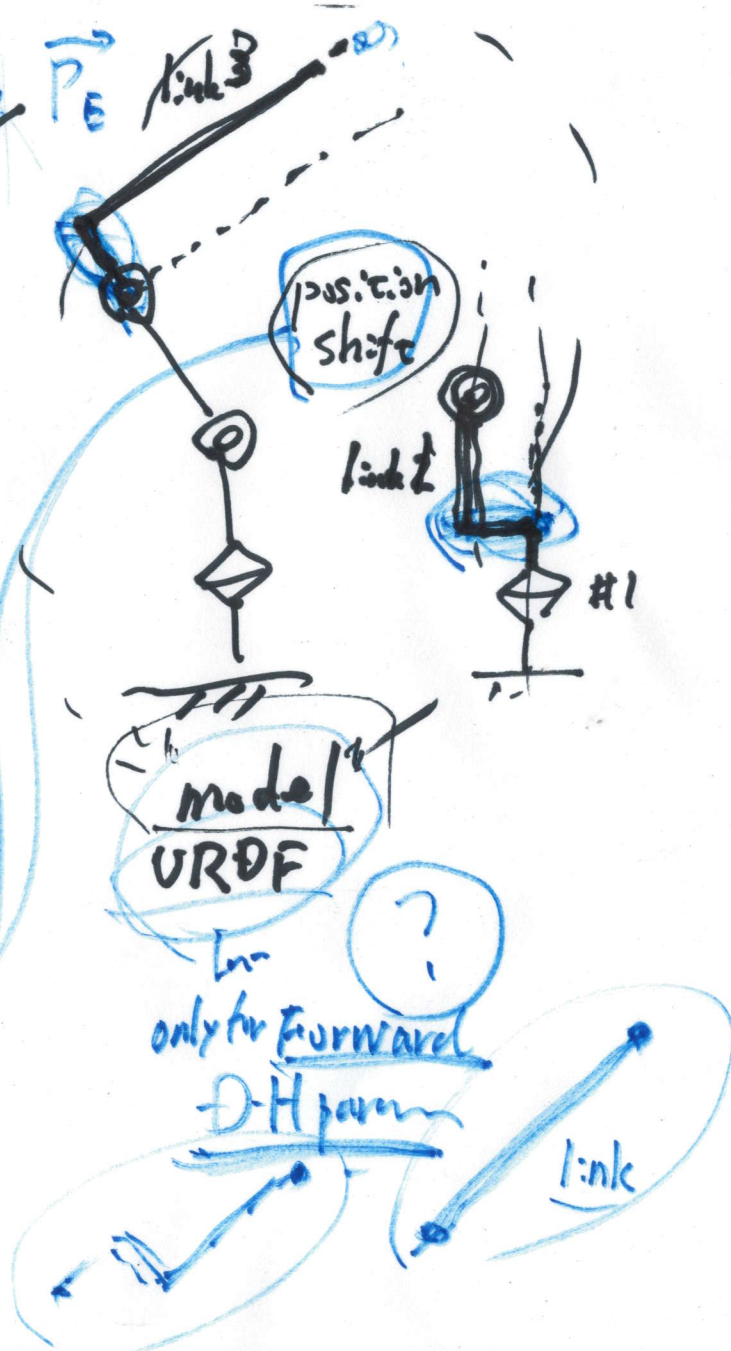
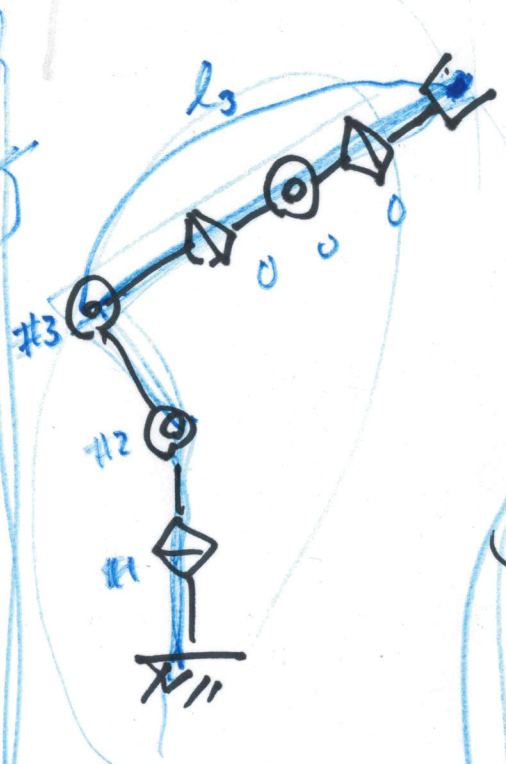


2026.01.14 Rb+(13) - 1/3



< Kinematic

x Inverse





2026.01.14 Rb+(13) - 3/3

