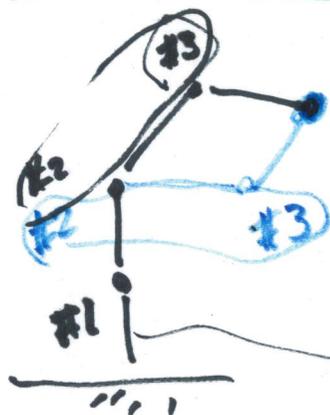
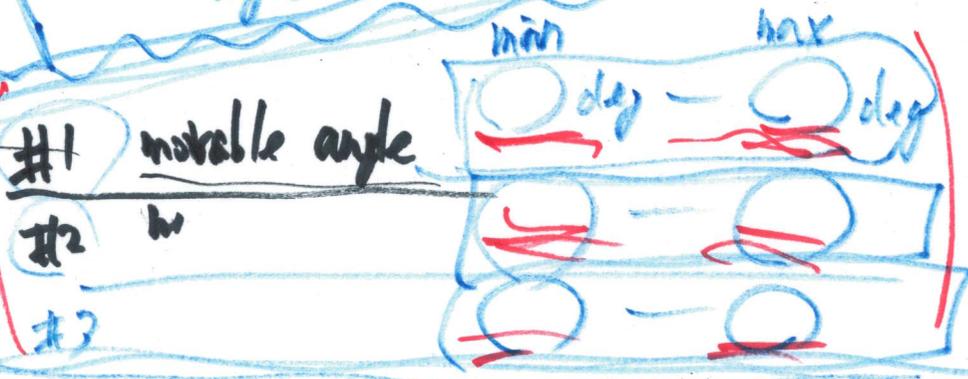


robot configuration

stick diagram



old angle
inverse kinem. slight diff
 new angle



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